INTRODUCTION TO ROBOTICS									
1	Course Title:	INTROD	UCTION TO ROBOTICS						
2	Course Code:	MAK408	1						
3	Type of Course:	Optional							
4	Level of Course:	First Cyc	le						
5	Year of Study:	4							
6	Semester:	7							
7	ECTS Credits Allocated:	3.00							
8	Theoretical (hour/week):	2.00							
9	Practice (hour/week):	0.00							
10	Laboratory (hour/week):	0							
11	Prerequisites:	Yok							
12	Language:	Turkish							
13	Mode of Delivery:	Face to f	face						
14	Course Coordinator:	Dr. Ögr.	Üyesi SEVDA TELLİ						
15	Course Lecturers:	Yok							
16	Contact information of the Course Coordinator:	E-Mail: sevda@uludag.edu.tr, Tel: 0 224 2941983 Adres: U.Ü.Müh.Mim.Fak.Makine Müh. Bölümü Görükle-BURSA							
17	Website:								
18	Objective of the Course:	This course aims to give the students the fundamental concepts of robotics. It covers robot kinematics and dynamics.							
19	Contribution of the Course to Professional Development:								
20	Learning Outcomes:								
		1	To able to introduce robots that are used very commonly in mechanical engineering, to the students during their training.						
		2	To gain basics knowledge to the students about the robot kinematics and dynamics.						
		3	To give opportunity to apply the subjects that are learned in the different courses and semesters, on a system .						
		4	To provide the ability to think and detection as an engineer.						
		5							
		6							
		7							
		8							
		9							
		10							
21	Course Content:								
		Co	ourse Content:						
Week	Theoretical		Practice						
1	Introduction								
2	Classifications of Robots, Basic Rob	ot Parts							
3	Robot Motion								
4	Industrial Manipulators								

5	Coordinate Transformations																		
6	Manipulator Kinematics																		
7	Inve	rse K	linem	atics															
8	Jacobian																		
9	Repeating courses and midterm exam																		
10	Velo	Velocity and Acceleration Analysis																	
11	Static Force Analysis																		
12	Dena	avit-H	larter	nberg l	Notati	on													
13	Manipulator Dynamics																		
14	Lagrangian Dynamics																		
22	Textbooks, References and/or Other Materials:						1) 2) 3) 4)	 Robotics: An Introduction, D.R.Malcolm Robotics: Basic Analysis and Design, W.A. Wolovich Mechanical Design of Robots, E.I. Rivin Robot Analysis and Control, H.Asada, J.E. Slotine. 											
23	Asse	esme	ent																
TERML	_EARI	NING	ACTI	VITIES			R			IGHT									
Midtern	n Exa	am					1		30	30.00									
Quiz							0		0.0	0.00									
Home v	work-	proje	ect				2		20	.00									
Final E	nal Exam 1 5						50	50.00											
Activites						1	Number			Dura	Duration (hour)			Total Work Load (hour)					
Epeore							50	50.00 2.00				28.00							
Practica	racticals/Labs						(0			0.00	0.00			0.00				
Self stu	elf study and preperation								14			1.00	1.00			14.00			
Homew	presurement and Evaluation Techniques Used in the meworks								2			15.00	15.00			30.00			
Pr 2 j4ect								(0			0.00	0.00			0.00			
Field S	Id Studies							(0 0.00			0.00							
Midtern	term exams							ŕ	1 8.00			8.00							
Others	ers							(0			0.00	0.00			0.00			
Final E	xams	;							ŀ	1			10.00	10.00			10.00		
Total W	Vork L	oad												90.00					
Total w	ork lo	bad/ :	30 hr													3.00			
ECTS (TS Credit of the Course											3.			3.00				
25	25 CONTRIBUTION OF LEARNING OUTCOMES TO PROGRAMME QUALIFICATIONS																		
	I	PQ1	PQ2	PQ3	PQ4	PQ5	PQ6	PQ7	PQ8	PQ9	PQ1 0	PQ11	PQ12	PQ1 3	PQ14	PQ15	PQ16		
ÖK1	(C	0	0	2	0	0	0	0	0	0	0	0	0	0	0	0		
ÖK2	(C	0	0	2	0	0	0	0	0	0	0	0	0	0	0	0		
ÖK3	Ę	5	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
ÖK4	3	3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		
	LO: Learning Objectives PQ: Program Qualifications																		

Contrib	1 very low	2 low	3 Medium	4 High	5 Very High
ution					
Level:					