	ELECTROMEC	HANIC	CAL CONTROL SYSTEMS							
1	Course Title:	ELECTR	ROMECHANICAL CONTROL SYSTEMS							
2	Course Code:	ELEZ20	5							
3	Type of Course:	Compuls	sory							
4	Level of Course:	Short Cy	/cle							
5	Year of Study:	2								
6	Semester:	3								
7	ECTS Credits Allocated:	4.00								
8	Theoretical (hour/week):	2.00								
9	Practice (hour/week):	0.00								
10	Laboratory (hour/week):	2								
11	Prerequisites:	None								
12	Language:	Turkish								
13	Mode of Delivery:	Face to	face							
14	Course Coordinator:	Öğr.Gör. HASAN BAYAZIT								
15	Course Lecturers:	Öğr.Gör. Ömer Eriş								
16	Contact information of the Course Coordinator:	hashan@uludag.edu.tr Tel: 2942345 Adres: U.Ü Teknik Bilimler MYO Görükle								
17	Website:									
18	Objective of the Course:	In this course, students will be able to assemble electromechanical control equipments and control one phase, three-phase asynchronous and direct current motors running, change the direction of the speed, braking operations using electromechanical components								
19	Contribution of the Course to Professional Development:									
20	Learning Outcomes:									
		1	Describes the control elements.							
		2	Describes the function of the Motor protection relays.							
		3	Be able to run asynchronous motors constantly, remotely as well as jogging.							
		4	Be able to construct control circuit related with the acceleration, change of direction and braking of three-phase asynchronous motors with different techniques.							
		5	Be able to construct motor accelerating and speed control circuit of wound round induction motors.							
		6	Be able to construct control circuit of two-speed asynchronous motors.							
		7	Be able to construct control circuits of accelerating and reversing direction of single phase induction motors.							
		8	Be able to construct control circuits of accelerating, reversing and braking of dc current motors.							
		9								
		10								
21	Course Content:									
		Co	ourse Content:							
Week	Theoretical		Practice							
1	Introduction									

2	Electromechanical control elements.		Introduction of control	elements.						
3	Motor protection relays.		Connection of the motor protection relay.							
4	Jogging and continuous operation in three-phase asynchronous motors. F operation of three-phase asynchronous motors from two different location.	Remote	Starting of Induction motor.							
5	Acceleration methods of Induction m	otors.	Resistor type Induction motor starters.							
6	Changing direction of rotation of thre asynchronous motors and braking.	e-phase	Star-delta starters.							
7	Speed control of three-phase asynchmotors.	nronous	Speed of the induction motor with inverter.							
8	Midterm exam.									
9	Acceleration methods of wound rou induction motors.	nd	Braking of three-phase	asynchronous moto	ors.					
10	Control of two-speed asynchronous	motors.	Two-speed motor cont	rol circuit.						
11	Control methods for single-phase asynchronous motors.		Changing the direction	of rotation of unive	rsal motor.					
12	Changing direction of rotation of a si phase asynchronous motors and brown of the same of		Single phase asynchro	onous motor brake co	ontrol circuit.					
13	Acceleration methods and control of current motors.	direct	Making connections of direct current motors.							
14	Changing direction of rotation of DC and braking.	motors	Dc motor brake control circuit.							
22 Activit	Textbooks, References and/or Other tes	•	Elektrik kumanda devr Number	eleri,2008, İlhami Ço Duration (hour)						
Theore	ical		E élétrik Tesisleri Laora	atu a r0Deneyleri,Bayra	ph21M0.0					
Practic	als/Labs		14	2.00	28.00					
Self stu	dy and preperation	NUMBE	14 WEIGHT	1.00	14.00					
Homev		11411141111	0	0.00	0.00					
Midtect	ng Exam	1	20 <u>2</u> 00	10.00	20.00					
Field S	tudies		0	0.00	0.00					
Modreen	workapneject	1	20100	7.00	7.00					
Others			0	0.00	0.00					
Fixtal E	xams	3	100.00	7.00	7.00					
	Vork Load				118.00					
Total w	rork load/ 30 hr				3.93					
ECTS	Credit of the Course				4.00					
Total			100.00							
Measu Course	rement and Evaluation Techniques U	sed in the								
24	ECTS / WORK LOAD TABLE									
25	CONTRIBUTION	OF LEA	RNING OUTCOME	S TO PROGRAM	1ME					

25	CONTRIBUTION OF LEARNING OUTCOMES TO PROGRAMME QUALIFICATIONS															
	PQ1	PQ2	PQ3	PQ4	PQ5	PQ6	PQ7	PQ8	PQ9	PQ1 0	PQ11	PQ12	PQ1 3	PQ14	PQ15	PQ16
ÖK1	2	0	0	0	1	0	5	0	2	0	0	0	0	0	0	0
ÖK2	2	0	0	0	3	0	5	0	3	0	0	0	0	0	0	0

ÖK3	3	0	0	0	4	0	5	0	5	0	0	0	0	0	0	0
ÖK4	0	0	0	0	1	0	5	0	1	0	0	0	0	0	0	0
ÖK5	2	0	0	0	3	0	5	0	4	0	0	0	0	0	0	0
ÖK6	2	0	0	0	3	0	5	0	4	0	0	0	0	0	0	0
ÖK7	2	0	0	0	3	0	5	0	4	0	0	0	0	0	0	0
ÖK8	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
LO: Learning Objectives PQ: Program Qualifications																
Contrib 1 very low ution Level:		2	2 low			3 Medium			4 High			5 Very High				