	ADVANCED TO	PICS	IN MACHINE DYNAMICS						
1	Course Title:	ADVANCED TOPICS IN MACHINE DYNAMICS							
2	Course Code:	MAK6218							
3	Type of Course:	Optional							
4	Level of Course:	Third Cycle							
5	Year of Study:	1							
6	Semester:	2							
7	ECTS Credits Allocated:	5.00							
8	Theoretical (hour/week):	3.00							
9	Practice (hour/week):	0.00							
10	Laboratory (hour/week):	0							
11	Prerequisites:	None							
12	Language:	Turkish							
13	Mode of Delivery:	Face to face							
14	Course Coordinator:	Prof. Dr. OSMAN KOPMAZ							
15	Course Lecturers:	Prof. Dr. OSMAN KOPMAZ							
16	Contact information of the Course Coordinator:	okopmaz@uludag.edu.tr +90 224 294 19 62 Uludağ Üniversitesi, Mühendislik Mimarlık Fakültesi, Makine Mühendisliği Bölümü, Görükle, 16059 Bursa							
17	Website:								
18	Objective of the Course:	In the design of machinery, dynamic analysis is one of the most important phases. The first stage of such an analysis is deriving equations of motion. In this course, various forms of formulations of equations of motion are given. Moreover, dynamics of some mechanisms and machines often encountered in mechanical engineering practice.							
19	Contribution of the Course to Professional Development:								
20	Learning Outcomes:								
		1	Students who attend this course can approach to machine dynamics problems with scientific methods, and use the softwares in this field more efficiently.						
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21	Course Content:								
		Co	ourse Content:						
Week	Theoretical		Practice						

1	Review of principles of dynamics and topics of machine dynamics. Static and dynamic equilibrium problems. Energi balancing. Mass balancing.	basic nd y				
2	Methods used in the derivation of equ of motion. Euler-Newton equations of 1st take-home.	uations motion.				
3	Principle of virtual work. Principle of v power (Jourdain principle).	virtual				
4	Generalized coordinates. D'Alembert principle. Lagrangian equations of mo 2nd take-home.	's otion.				
5	Hamilton principle. Generalized veloc Kane's equations of motion. Gibbs-Ap equations.	ities. opel				
6	Implementations in special mechanic systems. Holonom and non-holonom systems. 3rd take-home.	al				
7	Deriving and solving equations of mo systems with rigid and/or flexible bod	tion of ies.				
8	Repeating courses and midterm exar	n				
9	Dynamics of reciprocating machines. Kinematics and dynamics of a crank- mechanism.	slider				
10	First and second order crank stars. M energy balancing single and multi-cyl internal combustion engines. 4th take	lass and inder				
Activit	tes			Number	Duration (hour)	Total Work Load (hour)
Theore	by hamic analysis of cam mechanism	s. 5th		14	3.00	42.00
Practic	als/Labs			0	0.00	0.00
Self stu	Joy and preperation			14	5.00	70.00
Homev	vorks			5	15.00	75.00
Project	Materials:		S	gringer Verlag.	0.00 Machineny McGraw	0.00
Field S	Studies			0	0.00	0.00
Mi gig err	Assessment			1	2.00	2.00
Others				0	0.00	0.00
Final E	xams m Exam	R 1	21	1	2.00	2.00
Total V	Vork Load					191.00
Total w	vork load/ 30 hr	5	2			6.37
ECTS						
	Credit of the Course			7-337		5.00
Total	Credit of the Course	7	ی 10	00.00		5.00
Total Contrib	Credit of the Course	7 2010	J(1(5(00.00		5.00
Total Contrib Succes	Credit of the Course	7 es to	ر 10 50	0.00 0.00 0.00		5.00
Total Contrib Succes Contrib	Credit of the Course	7 es to	10 50 50	0.00 0.00 0.00 0.00		5.00
Total Contrib Succes Contrib Total	Credit of the Course	7 es to	50 50 10	5.00 00.00 0.00 0.00 0.00		5.00
Total Contrib Succes Contrib Total Measu Course	Credit of the Course	7 2s to e ed in the	1(5(1(5.00 00.00 0.00 0.00 0.00 0.00		5.00

25	CONTRIBUTION OF LEARNING OUTCOMES TO PROGRAMME QUALIFICATIONS															
	PQ1	PQ2	PQ3	PQ4	PQ5	PQ6	PQ7	PQ8	PQ9	PQ1 0	PQ11	PQ12	PQ1 3	PQ14	PQ15	PQ16
ÖK1	4	4	4	0	0	0	4	0	0	0	0	0	0	0	0	0
LO: Learning Objectives PQ: Program Qualifications																
Contrib ution Level:	1 very low				2 low			3 Medium		4 High		5 Very High				