MODERN CONTROL SYSTEMS										
1	Course Title:	MODERN CONTROL SYSTEMS								
2	Course Code:	MAK6237								
3	Type of Course:	Optional								
4	Level of Course:	Third Cycle								
5	Year of Study:	1								
6	Semester:	1								
7	ECTS Credits Allocated:	6.00	6.00							
8	Theoretical (hour/week):	3.00								
9	Practice (hour/week):	0.00								
10	Laboratory (hour/week):	0								
11	Prerequisites:	None								
12	Language:	Turkish								
13	Mode of Delivery:	Face to face								
14	Course Coordinator:	Prof. Dr. ELİF ERZAN ERZAN TOPÇU								
15	Course Lecturers:	Doç. Dr. Gürsel ŞEFKAT								
16	Contact information of the Course Coordinator:	Prof. Dr. Elif ERZAN TOPÇÜ e-posta: erzan@uludag.edu.tr Telefon: 0224 294 19 90 Adres: Bursa Uludağ Üniversitesi Mühendislik Fakültesi Makine Mühendisliği Bölümü Görükle/BURSA								
17	Website:									
18	Objective of the Course:	To examine the essential knowledge and skills that provide an understanding of the subject and functions of modern control systems with mathematical relations and simulation studies and to gain skills in related subjects								
13	Professional Development:	design. Know about control system design. Sliding mode control, fuzzy logic, etc., know intelligent control systems.								
20	Learning Outcomes:									
		1	Learn the basic concepts and definitions of the modern control system.							
		2	Know about control system design.							
		3	Know know intelligent control systems such as sliding mode control, fuzzy logic, etc.,							
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21	Course Content:									
\A/act	Theoretical	Co	Durse Content:							
vveek	k Theoretical Practice									

1	Introduction to modern control system	ns									
2	State Space Representation										
3	Establishing state space models for I time-invariant systems	inear									
4	Controllability, Stability and Observat	oility									
5	Optimal Control, LQR, Compensator	design									
6	Forward and feedback controller des linear time-invariant systems	ign for									
7	Forward and feedback controller des linear time-invariant systems (continu	ign for ıed)									
8	Controller design with root locus and frequency response methods										
9	Artificial Neural Networks (ANN), Ger Algorithms (GA)	netic									
10	Sliding mode controller design										
11	Sliding mode controller design (conti	nued) /									
Activit	ies			Number	Duration (hour)	Total Work Load (hour)					
Th leo re	Foatzy logic controller design (continu	ied)	Γ	14	3.00	42.00					
Practica	als/Labs			0	0.00	0.00					
Self stu	dy and preperation			14	3.00	42.00					
Homew	vorks		-	0	0.00	0.00					
Project	β		Ċ	tomatik Kontrol, Sisten	⁰ Dîhamiği ve Dene	tim Sistemleri,					
Field S	tudies			0	0.00	0.00					
Midtern	n exams		В	aski, Pearson Educatio	n control Systems	0.00					
Others				0	0.00	0.00					
Final E	xams		C	tomatik Kontrol, Sisten	୨ 9 inamiği ve Dene	tilfi Sistemleri,					
Total W	Vork Load					180.00					
Total w	ork load/ 30 hr		Ň	ATLAB ile Mühendislik	Sistemlerinin Anal	i⊉ive Çözümü,					
ECTS	Credit of the Course					6.00					
23	Assesment										
TERM L	EARNING ACTIVITIES	NUMBE R	W	/EIGHT							
Midterm Exam 1				0.00							
Quiz 0				0.00							
Home work-project 3				20.00							
Final E	xam	1	60.00								
Total		5	100.00								
Contrib Succes	oution of Term (Year) Learning Activitiess Grade	es to	40.00								
Contrib	oution of Final Exam to Success Grade	; 	60.00								

Total								10	100.00							
Measurement and Evaluation Techniques Used in the Course									Exam, homework and presentation							
24 EC	24 ECTS / WORK LOAD TABLE															
25	25 CONTRIBUTION OF LEARNING OUTCOMES TO PROGRAMME QUALIFICATIONS															
	PQ1	PQ2	PQ3	PQ4	PQ5	PQ6	PQ7	PQ8	PQ9	PQ1 0	PQ11	PQ12	PQ1 3	PQ14	PQ15	PQ16
ÖK1	4	0	3	0	0	0	2	0	0	0	0	0	0	0	0	0
ÖK2	4	0	2	0	0	0	2	0	0	0	0	0	0	0	0	0
ÖK3	4	1	3	0	0	0	2	0	0	0	0	0	0	0	0	0
LO: Learning Objectives PQ: Program Qualifications																
Contrib 1 ver ution Level:			low		2 low		3	Medi	um	ım 4 High		5 Very High				