COMPUTER CONTROLLED SYSTEMS Course Title: COMPUTER CONTROLLED SYSTEMS 1 Course Code: MAK5246 2 Type of Course: Optional 3 Level of Course: 4 Third Cycle Year of Study: 5 1 2 Semester: 6 ECTS Credits Allocated: 7 6.00 Theoretical (hour/week): 3.00 8 9 Practice (hour/week): 0.00 10 Laboratory (hour/week): 0 11 Prerequisites: Without prerequist 12 Language: Turkish Mode of Delivery: Face to face 13 Course Coordinator: Prof. Dr. İBRAHİM YÜKSEL 14 15 Course Lecturers: Yrd. Doç. Dr. Gürsel ŞEFKAT Contact information of the Course Prof. Dr. İbrahim YÜKSELİ 16 brahim@uludag.edu.tr +90 224 294 1972 Uludağ Üniversitesi Coordinator: Mühendislik – Mimarlık Fakültesi Makine Mühendisliği Bölümü 16059 Görükle/BURSA Website: 17 18 Objective of the Course: Explain the basic concepts such as discrete-time, z-transform, signal conversion (ADC, DAC), sampling time of the computer controlled systems. The design of the computer controlled system. Explanation of the basic properties of the data acquisition cards, real-time system design and measurement elements to be adapted to the system. Different control algorithms using MATLAB software, the establishment of practical systems in practice. Contribution of the Course to 19 Professional Development: 20 Learning Outcomes: To understate the discrete-time systems 1 2 To establish the computer-controlled control system as a theoretically. 3 To selection the sampling time and to interpret the effect of the system. 4 To prepare the program in MATLAB and to establish with Simulink model 5 To select and to establish the necessary infrastructure such as computer, interface, the control card and software. 6 To the design and realization of the Real time computer controlled systems that the system is modeled the theoretical 7 8 9 10 Course Content: 21 **Course Content:**

Week	Theoretical		Practice							
1	Introduction and basic elements of di time sample applications and digital o systems.	screte- control								
2	Signal transformation and selection or sampling time. Nyquist and Shannon theorems and properties of the samp frequency.	of the ling								
3	The computer oriented mathematical of discrete-time systems and z-Trans	models forms.								
4	Transfer functions, block diagrams an flow graph methods in discrete time s	nd signal systems.								
5	Determination of state variables and equations.	state								
6	Time domain, z domain and frequenc domain analysis.	су								
7	Data acquisition and / or control boar on features and peripherals (interface sensors, actuators) integration.	d based e,								
8	Introduction to MATLAB and Simulinl software, real-time programming.	k								
9	Repeating courses and midterm exar	n								
10	The solution of the system equations transform, and MATLAB / Simulink programming.	: Z-								
11 Activit	Design of discrete-time systems. es			Number	Duration (hour)	Total Work Load (hour)				
Theore	Real-time applications. MATLAB / Si	mulink,		14	3.00	42.00				
Practica	als/Labs			0	0.00	0.00				
Self_stu	Textbooks, References and/or Other		1.	Digital Control System	s; Benjamin C. Ku	84.00 dition,				
Homew	vorks			0	0.00	0.00				
Project	8		A	ström, B. Wittenmark,	3. Edition, Prentice	Hall, 1996				
Field S	tudies			0	0.00	0.00				
Midtern	n exams		4	Digital Control, K. Mo	ri, 2000 Adgalya, Wiley-Inte	3 dience, 2008				
Others				2	10.00	20.00				
Final E	kams			1	48.00	48.00				
Total W	/ork Load					218.00				
T BRAMW	BAR ROUND G3ACTIVITIES	NUMBE	W	EIGHT		7.27				
ECTS (Credit of the Course	<u>г т</u>		5.00		6.00				
Quiz		0	0.00							
Home v	vork-project	0	0.00							
Final E	xam	1	60.00							
Total		2	100.00							
Contrib Succes	ution of Term (Year) Learning Activitie s Grade	es to	40.00							
Contrib	ution of Final Exam to Success Grade)	60.00							
Total			1(100.00						
Measur Course	rement and Evaluation Techniques Us	sed in the								
24	ECTS / WORK LOAD TABLE									

25	CONTRIBUTION OF LEARNING OUTCOMES TO PROGRAMME QUALIFICATIONS															
	PQ1	PQ2	PQ3	PQ4	PQ5	PQ6	PQ7	PQ8	PQ9	PQ1 0	PQ11	PQ12	PQ1 3	PQ14	PQ15	PQ16
ÖK1	3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ÖK2	4	0	0	0	4	0	0	0	0	0	0	0	0	0	0	0
ÖK3	0	0	0	3	0	0	0	0	0	0	0	0	0	0	0	0
ÖK4	0	0	5	0	4	0	0	0	0	0	0	0	0	0	0	0
ÖK5	0	4	0	4	4	0	0	0	0	0	0	0	0	0	0	0
ÖK6	4	0	0	0	3	0	0	0	0	0	0	0	0	0	0	0
LO: Learning Objectives PQ: Program Qualifications												•				
Contrib ution Level:	1 very low				2 low		3 Medium			4 High			5 Very High			