MODERN CONTROL SYSTEMS										
1	Course Title:	MODER	N CONTROL SYSTEMS							
2	Course Code:	MAK623	7							
3	Type of Course:	Optional								
4	Level of Course:	Third Cy	cle							
5	Year of Study:	1								
6	Semester:	1								
7	ECTS Credits Allocated:	6.00								
8	Theoretical (hour/week):	3.00								
9	Practice (hour/week):	0.00								
10	Laboratory (hour/week):	0								
11	Prerequisites:	None								
12	Language:	Turkish								
13	Mode of Delivery:	Face to face								
14	Course Coordinator:	Prof. Dr. ELİF ERZAN ERZAN TOPÇU								
15	Course Lecturers:	Dr. Öğretim Üyesi Gürsel ŞEFKAT								
16	Contact information of the Course Coordinator:	erzan@uludag.edu.tr								
17	Website:									
18	Objective of the Course:	To examine the essential knowledge and skills that provide an understanding of the subject and functions of modern control systems with mathematical relations and simulation studies and to gain skills in related subjects								
19	Contribution of the Course to Professional Development:	Know the basic concepts and definitions of modern control system design. Know about control system design. Sliding mode control, fuzzy logic, etc., know intelligent control systems.								
20	Learning Outcomes:									
		1	Learn the basic concepts and definitions of the modern control system.							
		2	Know about control system design.							
		3	Know know intelligent control systems such as sliding mode control, fuzzy logic, etc.,							
		4								
		5								
		6								
		7								
		8								
		9								
		10								
21	Course Content:	_								
		Co	ourse Content:							
	Theoretical		Practice							
1	Introduction to modern control syste	ms								
2	State Space Representation									

3	Establishing state space models for time-invariant systems	linear								
4	Controllability, Stability and Observa	ability								
5	Optimal Control, LQR, Compensato	r design								
6	Forward and feedback controller del linear time-invariant systems	sign for								
7	Forward and feedback controller delinear time-invariant systems (contin									
8	Controller design with root locus and frequency response methods	d								
9	Artificial Neural Networks (ANN), Ge Algorithms (GA)	enetic								
10	Sliding mode controller design									
11	Sliding mode controller design (cont Image Processing	inued) /								
12	Fuzzy logic controller design									
13 Activit	Euzzy logic controller design (contin	ued)	1	Number	Duration (hour)	Total Work Load (hour)				
Th <b>2:2</b> re	itextbooks, References and/or Othe	r		aik ve Modern Kontro	გ <b>ეც</b> temi tasarımı,	42cen ERCAN				
Practic	IMatorials: als/Labs			<u>hh 2022                                 </u>	0.00	0.00				
Self stu	dy and preperation		Ibr	phim YUKSEL, 12. Bart and Rishon "Moder	ട്ടിപ്പ <sub>0</sub> Dora 2021.	42.00				
Homev	vorks			)	0.00	0.00				
Project	\$		Me	odern Control Enginee	წეფ K. Ogata, Pre	સાં <sub>કિલે</sub> Hall,				
Field S	tudies		(	)	0.00	0.00				
Midterr	n exams		Çö S=	zümlü Problemleri, İb NGİRGİN Gürsel SF	rahim YUKSEL, Me FKAT 4 Baskı Do	อินี่ ra 2016				
Others			(	)	0.00	0.00				
Final E	kams		libr	ahim YUKSEL, 5. Bas	86.00 ra 2017.	96.00				
Total V	Vork Load					180.00				
	PARNING ACTIVITIES	NUMBE	WE	EIGHT		6.00				
	Credit of the Course	11	120	00		6.00				
Midterm Exam 1 Quiz 0				0.00						
Home work-project 3				20.00						
Final Exam 1				60.00						
Total		5	10	100.00						
	oution of Term (Year) Learning Activit	ies to	40	40.00						
Contrib	oution of Final Exam to Success Grac	le	60	60.00						
Total			10	100.00						
Measu Course	rement and Evaluation Techniques U	Ised in the	Ex	Exam, homework and presentation						
24	ECTS / WORK LOAD TABLE	•								

25	CONTRIBUTION OF LEARNING OUTCOMES TO PROGRAMME QUALIFICATIONS															
	PQ1	PQ2	PQ3	PQ4	PQ5	PQ6	PQ7	PQ8	PQ9	PQ1 0	PQ11	PQ12	PQ1 3	PQ14	PQ15	PQ16
ÖK1	4	0	3	0	0	0	2	0	0	0	0	0	0	0	0	0
ÖK2	4	0	2	0	0	0	2	0	0	0	0	0	0	0	0	0
ÖK3	4	1	3	0	0	0	2	0	0	0	0	0	0	0	0	0
LO: Learning Objectives PQ: Program Qualifications																
Contrib 1 very low ution Level:		2	2 low		3 Mediur			4 High			5 Very High					